# On Relation Between Deformed Heisenberg Algebra And Finite Dimensional Lie Algebras

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Plan:

- Motivation
- Three dimensional Lie algebras for positive and even deformation function
- Four dimesional Lie algebra (extended Heisenberg algebra) for positive deformation function
- Final remarks

## **Motivation**

Let us recall some examples of deformed algebras: (1) two dimensional deformed space-time algebra - (*Majid*, *Ruegg*)

 $[x_0, x] = i \lambda x, \qquad \lambda \text{ real deformation parameter}$ 

(2) "Planck scale" quantum algebra (Majid)

 $[x, p] = i (1 - e^{-\lambda x}), \qquad (\hbar = c = 1)$ 

(3) deformed Heisenberg algebra with minimal length- (*Kempf*)

$$[x,p] = i \left(1 + \lambda^2 p^2\right)$$

(4) deformed two dimensional Borel algebras related with Jordanian twist (*Ogievetsky*)

$$[x,p] = \lambda p(p-1), \qquad [\sigma,x] = \lambda (1-e^{\sigma})$$

where  $\sigma = \ln p$ .

#### comments:

(i) in example (1) we deal with two-dimensional Lie algebra  $\mathfrak{aff}(\mathcal{R})$  of the group of all affine transformations of the real line

(ii) other examples are related to infinitedimensional Lie algebras

**remark**: In all presented two dimensional cases we deal with two variables x, p, a function f(p) and commutation relations in the form

$$[x, p] = i f(p)$$

Linearization of deformed algebra:

We assume that

- x, p and f(p) can be represented as hermitean operators  $\mathbf{X}, \mathbf{P}, \mathbf{F}$  in appropriate Hilbert space
- in "momentum" representation we have the following realizations

$$\mathbf{P} = p, \qquad \mathbf{F} = f(p), \qquad \mathbf{X} = i f(p) \frac{d}{dp}$$

acting on square integrable functions  $\phi(p) \in \mathcal{L}^2(-a, a; f)$  $(a \leq \infty)$  with the scalar product

$$\langle \psi , \phi \rangle = \int_{-a}^{a} \frac{dp}{f(p)} \psi^{*}(p) \phi(p)$$

#### remarks:

– because of positive definite scalar product we have

$$|\phi|^2 > 0 \implies f(p) > 0$$

- the hermiticity of X implies

$$\phi(-a) = \phi(a)$$
 or  $\phi(-a) = -\phi(a)$ 

Commutation relations

$$\begin{bmatrix} \mathbf{X} , \mathbf{P} \end{bmatrix} = i \mathbf{F}, \qquad \begin{bmatrix} \mathbf{P} , \mathbf{F} \end{bmatrix} = 0$$
$$\begin{bmatrix} \mathbf{X} , \mathbf{F} \end{bmatrix} = i f(p) f'(p) = i \mathbf{F}_1, \quad \begin{bmatrix} \mathbf{P} , \mathbf{F}_1 \end{bmatrix} = 0$$

In order to get a finite low-dimensional Lie algebra we require that algebra of three operators  $\mathbf{X}$ ,  $\mathbf{P}$  and  $\mathbf{F}$  is linear and to close this algebra we put

$$[\mathbf{X}, \mathbf{F}] = i f f' = i (\alpha + \beta p + \gamma f) = i (\alpha + \beta \mathbf{P} + \gamma \mathbf{F})$$

where  $\alpha$ ,  $\beta$  and  $\gamma$  are real parameters.

### Three dimensional Lie algebras

We consider the case of deformation function f(p) is positive and even function i.e. f(-p) = f(p) then

$$f(p)f'(p) = \beta p$$

and positive function of deformation

$$f(p) = \sqrt{1 + \beta p^2}$$

Lie algebra generated by  $\mathbf{X}, \mathbf{P}, \mathbf{F}$  satisfy the relations

$$[\mathbf{X}, \mathbf{P}] = i \mathbf{F}, \quad [\mathbf{X}, \mathbf{F}] = i \beta \mathbf{P}, \quad [\mathbf{P}, \mathbf{F}] = 0$$

with second order Casimir operator

$$C_2 = \mathbf{P}^2 - \frac{1}{\beta} \mathbf{F}^2$$

Let us redefine the generators  $(\beta=\pm\lambda^2)$ 

$$\mathbf{A}_3 \;=\; rac{1}{\lambda} \, \mathbf{X}\,, \quad \mathbf{P}_\pm \;=\; \mathbf{F} \pm \lambda \, \mathbf{P} \;=\; \mathbf{A}_2 \pm \mathbf{A}_1$$

commutation relations

$$egin{array}{rcl} \left[ \mathbf{A}_3 \,, \mathbf{P}_+ 
ight] &=& i \operatorname{sign}(eta) \left( \mathbf{A}_1 + \operatorname{sign}(eta) \, \mathbf{A}_2 
ight) \,, \ \left[ \mathbf{A}_3 \,, \mathbf{P}_- 
ight] &=& i \operatorname{sign}(eta) \left( \mathbf{A}_1 - \operatorname{sign}(eta) \, \mathbf{A}_2 
ight) \,. \end{array}$$

In this basis the Casimir operator take the form

$$C_{2}(\beta) = \mathbf{P}^{2} - \frac{1}{\beta} \mathbf{F}^{2} = \begin{cases} C_{2}(\lambda^{2}) \equiv \frac{1}{\lambda^{2}} \mathbf{P}_{+} \mathbf{P}_{-}; & \beta = \lambda^{2} > 0, \\ \\ C_{2}(-\lambda^{2}) \equiv \frac{1}{2\lambda^{2}} \left( \mathbf{P}_{+}^{2} + \mathbf{P}_{-}^{2} \right); \beta = -\lambda^{2} < 0. \end{cases}$$

Depending on sign of the deformation parameter  $\beta$  we get two types of three-dimensional Lie algebras:

(a) the case  $\beta > 0$  the algebra of inhomogeneous hyperbolic rotations of two-dimensional plane  $\mathfrak{iso}(1, 1)$  satisfying relations

$$[\mathbf{A}_3\,,\mathbf{P}_+]\ =\ i\,\mathbf{P}_+\,,\quad [\mathbf{A}_3\,,\mathbf{P}_-]\ =\ -i\,\mathbf{P}_-\,,\quad [\mathbf{P}_+\,,\mathbf{P}_-]\ =\ 0$$

explicit realization of generators in "momentum representation"

$$\mathbf{A}_3 = \frac{i}{\lambda} \sqrt{1 + \beta p^2} \frac{d}{dp}, \quad \mathbf{P}_{\pm} = \sqrt{1 + \lambda^2 p^2} \pm \lambda p = e^{\pm \operatorname{arcsh}(\lambda \mathbf{P})}$$

acting on the square integrable functions  $\phi \in \mathcal{L}^2(\mathfrak{R})$  with the scalar product

$$\langle \psi , \phi \rangle = \int_{-\infty}^{\infty} \frac{dp}{\sqrt{1 + \lambda^2 p^2}} \psi^*(p) \phi(p)$$

(b) the case  $\beta < 0$  the algebra of inhomogeneous rotations of two-dimensional Euclidean plane  $\mathfrak{iso}(2)$  satisfying relations

$$[\mathbf{A}_3, \mathbf{P}_+] = i \mathbf{P}_-, \quad [\mathbf{A}_3, \mathbf{P}_-] = -i \mathbf{P}_+, \quad [\mathbf{P}_+, \mathbf{P}_-] = 0$$

explicit realization of generators

$$\mathbf{A}_3 = \frac{i}{\lambda} \sqrt{1 - \beta p^2} \frac{d}{dp}, \quad \mathbf{P}_{\pm} = \sqrt{1 - \lambda^2 p^2} \pm \lambda p = e^{\pm \operatorname{arcsh}(\lambda \mathbf{P})}$$

Hermicity condition of generators implies that  $-1 \leq \lambda p \leq 1$  and they acting on the square integrable functions  $\phi \in \mathcal{L}^2(-1/\lambda, 1/\lambda)$  with the scalar product

$$\langle \psi, \phi \rangle = \int_{-1/\lambda}^{1/\lambda} \frac{dp}{\sqrt{1-\lambda^2 p^2}} \psi^*(p) \phi(p)$$

### Four dimensional Lie algebra

We assume that deformation function f(p) = 1 + w(p) is positive then

$$f(p)f'(p) = (1 + w(p))w'(p) = w(p)$$

and positive function of deformation is given by

$$f(p) = 1 + W(e^{p+a}) = 1 + w(p)$$

with arbitrary real constant  $a \in \mathcal{R}$  and function W(z)is the *Lambert function*. The function W(z) is positive and increasing function (concave) on positive semi-axis  $z \in \mathcal{R}_+$ .

Lie algebra is generated by

$$\mathbf{P} = p, \quad \mathbf{F} = w(p), \quad \mathbf{X} = i(1+w(p))\frac{d}{dp}$$

and satisfy the commutation relations

 $[\mathbf{X},\mathbf{P}] = i (\mathbf{I} + \mathbf{F}), \quad [\mathbf{X},\mathbf{F}] = i \mathbf{F}, \quad [\mathbf{P},\mathbf{F}] = 0$ 

equivalently, introducing generator  $\mathbf{\Pi} = \mathbf{P} - \mathbf{F}$ 

$$[{f X}\,,{f \Pi}] \;=\; i\,{f I}\,, \quad [{f X}\,,{f F}] \;=\; i\,{f F}\,, \quad [{f \Pi}\,,{f F}] \;=\; 0$$

remarks:

(i) operators  $\mathbf{X}$ ,  $\mathbf{\Pi}$  generate three dimensional Heisenberg algebra ( $\mathbf{X}$ ,  $\mathbf{\Pi}$ ,  $Z = \mathbf{I}$ )

(ii) operators  $\mathbf{X}, \mathbf{F}$  generate two-dimensional algebra  $\mathfrak{aff}(\mathcal{R})$ 

some comments on the Lambert function W(z):



The Lambert function W(z) is one-to-one on positive real axis  $0 \le z < \infty$  and the inverse function of  $z \to ze^z$  i.e.

$$W(ze^z) = z$$

and the following relations hold

$$W(z) e^{W(z)} = z, \quad W'(z) \equiv \frac{dW}{dz} = \frac{e^{-W(z)}}{1 + W(z)}$$
$$W''(z) = -(W'(z))^2 \left(\frac{2 + W(z)}{1 + W(z)}\right)$$

The last relation tell us that because the function W(z) is nonnegative on the positive real line, therefore W''(z) < 0 and  $W(z), z \in \mathcal{R}_+$  is concave.

The first two formulae imply that

$$z \ (1+W(z)) \frac{dW(z)}{dz} = W(z)$$

Assuming that  $z = e^{p+a}$ ,  $a \in \mathcal{R}$  and  $w(p) = W(e^{p+a})$  we get

$$(1+w(p))\frac{dw(p)}{dp} = w(p)$$

explicit differential realization of generators

$$\mathbf{P} = p, \quad \mathbf{F} = W(e^{p+a}), \quad \mathbf{X} = i \left(1 + W(e^{p+a})\right) \frac{d}{dp}$$

acting on the square integrable functions  $\phi \in \mathcal{L}^2(\mathcal{R})$ with the scalar product

$$\langle \psi, \phi \rangle = \int_{-\infty}^{\infty} \frac{dp}{1 + W(e^{p+a})} \psi^*(p) \phi(p)$$

or changing the variables  $p \to \xi$ 

$$\xi = p - W(e^{p+a}), \quad p = \xi + e^{\xi}$$

we get an equivalent differential realization of generators

$$\mathbf{X} = i \frac{d}{d\xi}, \quad \mathbf{P} = \xi + e^{\xi}, \quad \mathbf{F} = 1 + e^{\xi}$$

explicit matrix realization of generators

Four dimensional algebra  $\mathfrak{H}^{ext}$  (extended Heisenberg algebra) generated by  $X, \Pi, Z, F$  with non-vanishing commutation relations

$$\left[ {f X}\,, {f \Pi} 
ight] \;=\; {f Z}\,, \qquad \left[ {f X}\,, {f F} 
ight] \;=\; {f F}$$

can be realized by  $5 \times 5$  non-hermitian matrices

where  $x, \pi, z, \varphi \in \mathcal{R}$  and

$$\left[V(x,\pi,z,\varphi), V(x',\pi',z',\varphi')\right] = (x\pi'-x'\pi) Z + (x\varphi'-x'\varphi) F$$

conclusion: algebra  $\mathfrak{H}^{ext}$  is *solvable*.

### **Final remarks**

We conclude that by linearization of deformation function we get the following

### low dimensional Lie algebras

$$\begin{aligned} 2 - dimensional & 3 - dimensional & 4 - dimensional \\ [X, P] &= P & [X, P] &= F & [X, \Pi] &= Z \\ [X, F] &= P & [X, F] &= F \\ f(p) &= p & f(p) &= \sqrt{1 + \beta p^2} & f(p) &= 1 + W(e^{p+a}) \\ \mathfrak{sso}(2) &\sim \mathfrak{so}(2) &\ni \mathfrak{t}^2 & \mathfrak{H}^{ext} \\ \mathfrak{sso}(1, 1) &\sim \mathfrak{so}(1, 1) &\ni \mathfrak{t}^2 & \mathfrak{H}^{ext} \end{aligned}$$

where B(2) is two dimensional Borel Lie algebra.

#### Partially based on the article:

A.N. and V.M. Tkachuk, J. Phys. A 47 (2014) 025207